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Probabilistic Segmentation of Auditory Cues based on a Mixture of von Mises Distributions

8th AABBA General Meeting

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- 2 Binaural Front-End
- **3** Probabilistic Circular Clustering
- 4 Evaluation and Outlook



Introduction



Figure: Application scenario: segmentation of auditory cues for multiple sound sources at different angular positions w.r.t. the listener.



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Figure: Distribution of binaural cues and estimated relative azimuth angles for three speech sources positioned at -60° , 0° and 60° w.r.t. the look direction.

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Binaural Front-End



See also: http://twoears.aipa.tu-berlin.de/doc/1.0/afe/



Binaural Front-End

Mapping binaural cues to relative azimuth angles using polynomial regression:

$$\phi_{kl} = w_0^{(l)} + \sum_{i=1}^{P} w_i^{(l)} \tau_{kl}^i + \sum_{j=1}^{P} w_{P+j}^{(l)} \delta_{kl}^j$$
$$= w_l^T x_{kl}$$

with $\boldsymbol{w}_l^T = \begin{bmatrix} w_0^{(l)} & \cdots & w_{2P}^{(l)} \end{bmatrix}^T$, $\boldsymbol{x}_{kl} = \begin{bmatrix} 1 & \tau_{kl} & \cdots & \tau_{kl}^P & \delta_{kl} & \cdots & \delta_{kl}^P \end{bmatrix}^T$

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Training setup:

- Anechoic HRTF's (KEMAR dummy head)
- 180 relative azimuth angles (1° increment)
- White noise as stimulus signal
- Individual models are trained for each filterbank channel/center frequency





Probabilistic Circular Clustering

The von Mises distribution:

$$\mathcal{VM}(\phi \mid \mu, \kappa) = \frac{1}{2\pi I_0(\kappa)} \exp\left\{\kappa \cos(\phi - \mu)\right\}$$





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Mixture of von Mises distributions:

$$p(\phi \mid \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\kappa}) = \sum_{m=1}^{M} \pi_m \mathcal{VM}(\phi \mid \mu_m, \kappa_m)$$
$$\boldsymbol{\pi} = [\pi_1, \dots, \pi_M]^T$$
$$\boldsymbol{\mu} = [\mu_1, \dots, \mu_M]^T$$
$$\boldsymbol{\kappa} = [\kappa_1, \dots, \kappa_M]^T$$





Expectation maximization for circular clustering:

Inputs:

Number of sound sources M

Estimated target source azimuth ϕ_T

Estimated azimuth angles for all T-F units as a vector $\phi \in \mathbb{R}^{N_{S}}$, $N_{S} = K \cdot L$ Initialization: Run circular k-means to initialize π_{m} , μ_{m} , κ_{m} and γ_{im} repeat

E-Step:

Compute responsibilities
$$\gamma_{im} = \frac{\pi_m \mathcal{VM}(\phi_i \mid \mu_m, \kappa_m)}{\sum_{j=1}^M \pi_j \mathcal{VM}(\phi_i \mid \mu_j, \kappa_j)}$$

M-Step:

Re-estimate circular means:

$$\mu_m = \begin{cases} \phi_T, & \text{if } m = 1\\ \operatorname{atan2}\left(\sum_{i=1}^{N_{\mathrm{s}}} \gamma_{im} \sin(\phi_i), \sum_{i=1}^{N_{\mathrm{s}}} \gamma_{im} \cos(\phi_i)\right), & \text{otherwise} \end{cases}$$

Re-estimate concentration parameters $\kappa_m = A^{-1} \left(\frac{\sum_{i=1}^{N_s} \gamma_{im} \cos(\phi_i - \mu_m)}{\sum_{i=1}^{N_s} \gamma_{im}} \right)$

Re-estimate mixture proportions $\pi_m = \frac{1}{N_s} \sum_{i=1}^{N_s} \gamma_{im}$ Evaluate the log-likelihood $\mathcal{L}(\phi \mid \pi, \mu, \kappa) = \log \left(p(\phi \mid \pi, \mu, \kappa) \right)$ until $\mathcal{L}(\phi \mid \pi, \mu, \kappa)$ converges



Probabilistic Circular Clustering



Figure: Starting point for EM algorithm ($\kappa_i = 0 \forall i$).



Probabilistic Circular Clustering



Figure: EM algorithm initialized with circular k-means.



Probabilistic Circular Clustering



Figure: EM algorithm after one iteration.



Probabilistic Circular Clustering



Figure: EM algorithm after five iterations.



Probabilistic Circular Clustering



Figure: EM algorithm after ten iterations.



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- After EM has converged, weights can be computed for each T-F unit:

$$\alpha_{kl}^{(m)} = \frac{\pi_m \mathcal{VM}(\phi_{kl} \mid \mu_m, \kappa_m)}{\sum_{i=1}^M \pi_i \mathcal{VM}(\phi_{kl} \mid \mu_i, \kappa_i)}$$

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 \blacksquare Hence, the soft-mask for the m-th source is specified as

$$\boldsymbol{A}_{m} = \begin{bmatrix} \alpha_{11}^{(m)} & \cdots & \alpha_{K1}^{(m)} \\ \vdots & \ddots & \vdots \\ \alpha_{1L}^{(m)} & \cdots & \alpha_{KL}^{(m)} \end{bmatrix}$$

Experimental setup:

- \blacksquare One target source (speech) at 0° relative azimuth
- \blacksquare Two maskers (white noise) at -60° and 60° relative azimuth and 0dB SNR
- Anechoic conditions (KEMAR HRTF's from [Wierstorf et al. (2011)])
- Relative azimuth of the target source is assumed to be known, but localization performance is artificially degraded: $\phi_T + \mathcal{N}(0, \sigma_{\phi}^2)$



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Evaluation and Outlook

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Evaluation and Outlook

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• Extensive evaluation of the proposed framework with different sound types and more challenging acoustic conditions.

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